

**IN THE CLAIMS:**

Please amend Claims 2 and 3 as follows:

Claims 1 and 4 (cancelled).

Claim 2. (currently amended): An apparatus for controlling a plurality of hydraulic motors and a clutch in which a single driving shaft is driven by outputs of a plurality of hydraulic motors, and one of the plurality of hydraulic motors drives the driving shaft through the clutch, comprising:

a first servo valve that controls the tilt rotation amount of a first hydraulic motor, and sets the tilt rotation amount of the first hydraulic motor to a zero tilt rotation amount when a zero fixing pressure,  $\{Pcs=Pf\}_1$ , of a predetermined value is input;

a clutch that is disengaged when a release pressure,  $\{Pk\}_1$ , of a predetermined value that is larger than the zero fixing pressure,  $\{Pf\}_1$ , of the predetermined value is input;

hydraulic vehicle speed detecting means for detecting a vehicle speed by a vehicle speed signal pressure,  $\{Pv\}_1$ , based on a vehicle speed; and

control valve means that releases an output command pressure,  $\{Pcs\}_1$ , to a return pressure,  $\{Pt\}_1$ , connected to a tank until a vehicle speed signal pressure,  $\{Pv\}_1$ , received from the hydraulic vehicle speed detecting means reaches a start pressure,  $\{Pb\}_1$ , of a predetermined value, and begins to output the command pressure,  $\{Pcs\}_1$ , to the first servo valve and the clutch when the vehicle speed signal pressure,  $\{Pv\}_1$ , exceeds a predetermined value.

Claim 3. (Currently amended): An apparatus for controlling a plurality of hydraulic motors and a clutch according to claim 2, ~~in which a single driving shaft is driven by outputs of a plurality of hydraulic motors, and one of the plurality of hydraulic motors drives the driving shaft through the clutch; further~~ comprising:

~~a first servo valve that controls the tilt rotation amount of a first hydraulic motor, and sets the tilt rotation amount of the first hydraulic motor to a zero tilt rotation amount when a zero fixing pressure ( $P_{cs}=P_f$ ) of a predetermined value is input;~~

a zero tilt rotation detecting valve that detects the tilt rotation amount of the first hydraulic motor, and causes a command pressure,  $(P_{cs})_1$  to be in communication with the clutch to disengage the clutch when the zero tilt rotation amount is detected;

~~hydraulic vehicle speed detecting means for detecting a vehicle speed by a vehicle speed signal pressure ( $P_v$ ) based on a vehicle speed; and~~

control valve means that releases an output command pressure,  $(P_{cs})_1$  to a return pressure,  $(P_t)_1$  connected to a tank until a vehicle speed signal pressure,  $(P_v)_1$  received from the hydraulic vehicle speed detecting means reaches a start pressure,  $(P_b)_1$  of a predetermined value, and begins to output the command pressure,  $(P_{cs})_1$  to the first servo valve and the zero tilt rotation detecting valve when the vehicle speed signal pressure,  $(P_v)_1$  exceeds a predetermined value.